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Cloud Accelerated

Cyborg Project Year 1 Review





Why Cyborg As A New Project

WHY CYBORG AS A NEW OPROJECT

 Acceleration has become a necessity rather than an interesting option

BACKGROUND: HISTORY

- OpenStack Acceleration Discussion Started from Telco Requirements
 - High level requirements first drafted in the standard organization ETSI NFV ISG
 - High level requirements transformed into detailed requirements in OPNFV DPACC project.
 - New project called Nomad established to address the requirements.
 - BoF discussions back in OpenStack Austin Summit.







BACKGROUND: HISTORY

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- Transition to Cyborg Project
 - After a long period of discussions within the OpenStack community, we discovered that the initial goal of Nomad project to address acceleration management in Telco was too limited. Developers from Scientific WG help us understand the need for acceleration management in HPC cloud at the Barcelona Design Summit which also led to a lot of discussion on the Public Cloud support of accelerated instances.
 - The aforementioned discussions led us to formally establish a project that will work on the management framework for dedicated devices in OpenStack called the Cyborg Project.







BACKGROUND: HISTORY



http://fandom.wikia.com/articles/martian-manhunter-replaced-cyborg-justice-league-founder



BACKGROUND: OPENSTACK SCIENTIFIC WG FEEDBACK ON GPU

- GPUs *can* be used in openstack.
 - GPU specific flavors: pci_passthrough alias need to be populated in the properties field of extra_specs for the specific instance
 - KVM tuning is required to achieve acceptable performance
- Two options:
 - Heterogeneous hosts: GPU and CPU-only hosts mixed
 - Good CPU resources are available for all workloads
 - Bad scheduler does not prioritize GPU workloads.
 - GPU only Host-Aggregate: GPU hosts are segregated
 - Good GPU hosts are only used for GPU workloads
 - Bad CPU-only workloads unable to use underutilized GPU hosts



USE CASES FOR CYBORG OPERATORS



What we actually want from a project like Cyborg:

- List accelerators
 - (cyborg accelerator list --feature-tag DEEP_LEARNING)
- Identify and discover attached accelerators
 - (cyborg accelerator discover)
- Attach and detach accelerators to an instance
 - (cyborg accelerator attach --instance-id FPGA_VF_1)
- Install and uninstall a driver
 - (cyborg accelerator install --driver-id SPDK_Driver)







WHAT (CYBORG OVERVIEW)



 Cyborg is a general management framework

for accelerators

 We have the LONGEST team meetings







ARCHITECTURE









TIMELINE





TIMELINE (PLANNED)

MAY 2018	SEP	2018	NOV 2018		
OpenStack Vancouver Summit Rocky Spec Freeze	OpenStack Rocky Release Denver PTG for Stein		KubeCon Shanghai Summit OpenStack Berlin Summit		
				Dec	Feb
	AUG 2018 K8s proposal ready for review			DEC 2018 KubeCon NA K8s cyborg solutior release	1 alpha







OPEN COMMUNITY

• Development:

https://review.openstack.org/#/q/status:open+project:openstack/cyborg

- Use openstack-dev mailing list with [acceleration] or [Cyborg]
- Wiki at https://wiki.openstack.org/wiki/Cyborg
- Weekly irc meeting at #openstack-cyborg
- <u>Stats</u>
- Looking for more resources
- Give a shout out at #openstack-cyborg













WHAT (CYBORG PIKE RELEASE)



Cyborg Pike release with its basic framework ready



CYBORG PIKE RELEASE













PIKE RELEASE

- Self Release
 - Basic framework
 - REST API
 - Conductor & Agent
 - Generic Stub Driver
 - Devstack Plugin
 - Initial docs and testing materials



WHAT (CYBORG QUEENS RELEASE)



Cyborg's first official release with resource provider data model available and some initial drivers

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CYBORG QUEENS RELEASE





QUEENS RELEASE

- First Official Release
 - Denver PTG discussion: <u>https://etherpad.openstack.org/p/cyborg-queens-ptg</u>
 - Key Features:
 - Resource Provider data model in cyborg DB
 - Interaction with Placement API and resource report
 - Intel FPGA driver
 - SPDK driver



WHAT (CYBORG ROCKY RELEASE)



WHAT (CYBORG ROCKY RELEASE)

Many items planned for Rocky release



CYBORG ROCKY PLANNING (OPENSIALIN)









CYBORG ROCKY PLANNING (KUBERNETE



- Align Cyborg data model with DPI before 1.13 release
- Cyborg DPI Plugin ready when DPI GA
- Consider the possibility of a CRD Acc controller

containerized



OTHER FUTURE PLANS FOR CYBUKG



- Rocky Release Planning with additional ARM collaboration
- Consider the possibility of a CRD Acc controller







HOW



Cyborg could be used together with Nova or standalone for bare metal







NOVA INTERACTION EXAMPLE





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WHERE



Possible ideas for Cyborg ARM collaboration



CYBORG ROCKY RELEASE PLANNING WI Dependent Days ADDITIONAL ARM COLLABORATION



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PAC









SMARTNIC









QAT



INTEL® QUICKASSIST TECHNOLOGY IS DESIGNED TO OPTIMIZE THE USE & DEPLOYMENT of Crypto and compression hardware accelerators on intel® platforms







VCA









FPGA Orchestration - Architecture Components







Cloud Use Cases



FPGA PCIe Device

Virtualized FPGA PCIe Device





Cloud Use Cases

FPGA as a Service

Give me a region of type X

Programming security is paramount!

- Request-time Programming
 - User request includes bitstream ID
 - Infra programs bitstream
- Runtime Programming
 - VM requests bitstreams at runtime
 - Infra handles the requests

Accelerated Function as a Service

Give me an instance of ipsec

Need to say what device's drivers are in the VM

Operator Model:

- Pre-programmed: For Simplicity, Security, Peak provisioning ...
- Orchestrator-programmed: If not available, program an unused region.







AFaaS: Pre-programmed









AFaaS: Orchestrator-Programmeu

Flavor extra specs: resource:CUSTOM_ACCELERATOR=1 trait:CUSTOM_FPGA_INTEL_PAC_ARRIA10=required function:CUSTOM_FPGA_INTEL_<ipsec-uuid>=required

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FPGAaaS: Request specifies a bill of the and the second se





FPGAaaS: Bitstreams programmed at rul



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QUESTIONS?

Ask on #openstack-cyborg IRC channel







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Thank You